

7.6 Moments, Centers of Mass, Centroids

Force=mass x acceleration

$$F=Ma$$

Moments & Center of Mass for a 1D system:

Let $m_1, m_2, m_3, \dots, m_n$ be located at positions $x_1, x_2, x_3, \dots, x_n$.

1. The moment about the origin, $M_0 = m_1x_1 + m_2x_2 + m_3x_3 + \dots + m_nx_n$.

2. The center of mass or center of gravity $\bar{x} = M_0/m$, where $m = m_1 + m_2 + m_3 + \dots + m_n$ is the total mass of the system.

ex. A 12 cm beam of a mobile has masses 10units, 15 units, 5 units, and 10 units located at one end, 5cm, 9cm, and 12cm from that end. Find the center of mass.

Moments & Center of Mass for a 2D system:

Let m_1, m_2, \dots, m_n be located at $(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$.

1. The moment about the y axis, $M_y = m_1x_1 + m_2x_2 + \dots + m_nx_n$.
2. The moment about the x axis, $M_x = m_1y_1 + m_2y_2 + \dots + m_ny_n$.
3. The center of mass or center of gravity is (\bar{x}, \bar{y}) where $\bar{x} = M_y/m$, $\bar{y} = M_x/m$, and $m = m_1 + m_2 + m_3 + \dots + m_n$ is the total mass of the system.

ex. A platter holds items of mass $m_1=6$, $m_2=3$, $m_3=2$, and $m_4=9$ located at $(3,-2)$, $(0,0)$, $(-5,3)$, and $(4,2)$. Locate the spot where an acrobat is to place her finger so as to balance the platter.

Moments and Center of mass of a planar lamina

Let f & g be continuous functions that bound a region (planar lamina) of uniform density ρ such that $f(x) \geq g(x)$ on $[a, b]$.

1. The moment about the x axis is $M_x = \rho \int_a^b \left[\frac{f(x)+g(x)}{2} \right] [f(x)-g(x)] dx$

2. The moment about the y axis is $M_y = \rho \int_a^b x[f(x)-g(x)] dx$

3. The center of mass or center of gravity is (\bar{x}, \bar{y})

where $\bar{x} = M_y/m$, $\bar{y} = M_x/m$, and

$$\mathbf{m} = \rho \int_a^b [f(x)-g(x)] dx$$

is the total mass of the system.

ex. Find the center of mass of the lamina of uniform density ρ bounded by $y = 9 - x^2$ and the x axis.